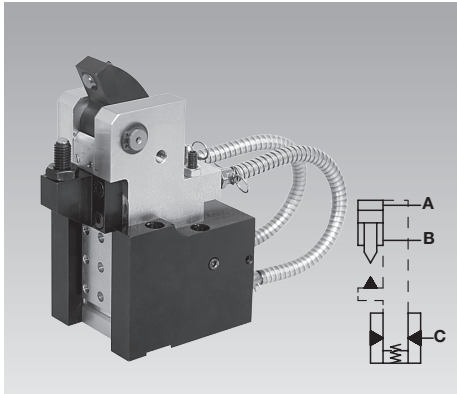


Position Flexible Clamping Claw

double acting, separate locking port,
with optional position monitoring, max. operating pressure 250 bar



Application

Position flexible clamping elements can be used for supporting and clamping of unstable workpiece sections. They adapt themselves to the position of the clamping point without deforming them. They cushion vibrations and compensate machining forces from all directions.

Description

The position flexible clamping claw consists of a U-shaped mounting body and the displaceably embedded clamping unit with oil supply by two short high-pressure hoses with swarf protection.

In the movable clamping unit a double-acting hydraulic cylinder is integrated, whose clamping force is introduced through the clamping lever by 180° into the workpiece support. This support is height-adjustable to clamp workpieces of different thickness.

After the clamping process, the still displaceable clamping unit will be locked by a single-acting cylinder in the mounting body. In unclamped mode, the clamping lever swivels back so far that unimpeded loading and unloading of the clamping fixture can be effected. An inductive or pneumatic position monitoring can be delivered to control the clamping lever.

Position flexible clamping

For machining in a clamping fixture in 3 levels, a workpiece will be positioned and clamped against a maximum of 5 support and location points. If further sections of the workpiece have to be supported and clamped, additional work supports will be used, on top of which also clamping can be effected.

Problem: If the sections to be clamped are very unstable, the contact of the support plunger already causes deformation. If the following clamping is effected, the caused deformation will not be calculable. Variations at the finish-machined workpiece are not acceptable.

Solution: Using position flexible clamping elements at such critical points can considerably improve the result.

Advantages

- Clamps position flexibly within the pendulum range
- Workpiece support points are adjustable and mountable in 4 positions
- Unimpeded loading and unloading of the fixture
- Very low displacement forces act on the workpiece
- Adjustable zero position
- Compensation of machining forces from all directions
- Monitoring of the unclamping position and the end of the clamping stroke can be effected pneumatically or inductively
- The clamping lever can be swivelled into small recesses
- Double-acting clamping function
- The locking port can be controlled separately
- Oil supply alternatively via pipe threads or drilled channels
- Connecting hoses with swarf protection
- Air sealing connection to avoid entry of swarf and coolants

Example:

 (see figure on the top right)

A workpiece is clamped in a fixture. For machining a relatively unstable web, clamping with minimum deformation is required. A position flexible clamping claw is arranged so that the web is within the clamping range.

First, the clamping cylinder is controlled. By nipper-like "floating" clamping, the web will be clamped between the support and the clamping lever, i.e. the clamping unit adapts itself position flexibly to the height. The occurring displacing force in the mounting body will be minimised by the installed weight compensation.

Then the clamping unit is locked by a second clamping circuit or a sequence valve and can now compensate machining forces from all directions.

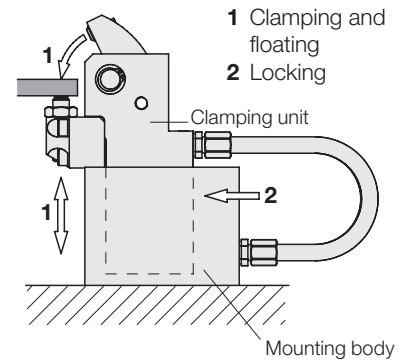
Important notes

The position flexible clamping claw has to be checked regularly about contamination by swarf and cleaned, if required. Regular lubricating reduces the displacing forces on the workpiece during clamping.

The smaller the distance between the workpiece and the workpiece support point, the smaller the displacing force onto the workpiece during clamping (see contact force).

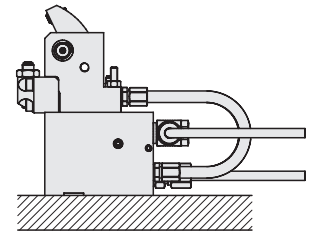
Air sealing increases the life and the sensitivity of the clamping element.

The clamping unit made of aluminium has to be highly protected against abrasive swarf.

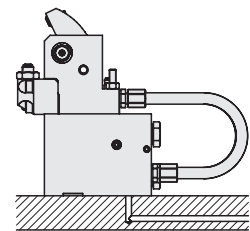


Connecting possibilities

Pipe thread

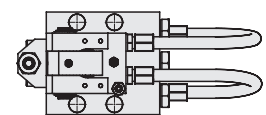


Drilled channels

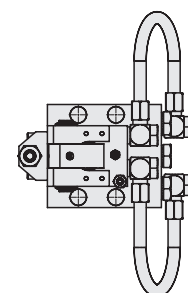


Design possibilities

Hose at the back



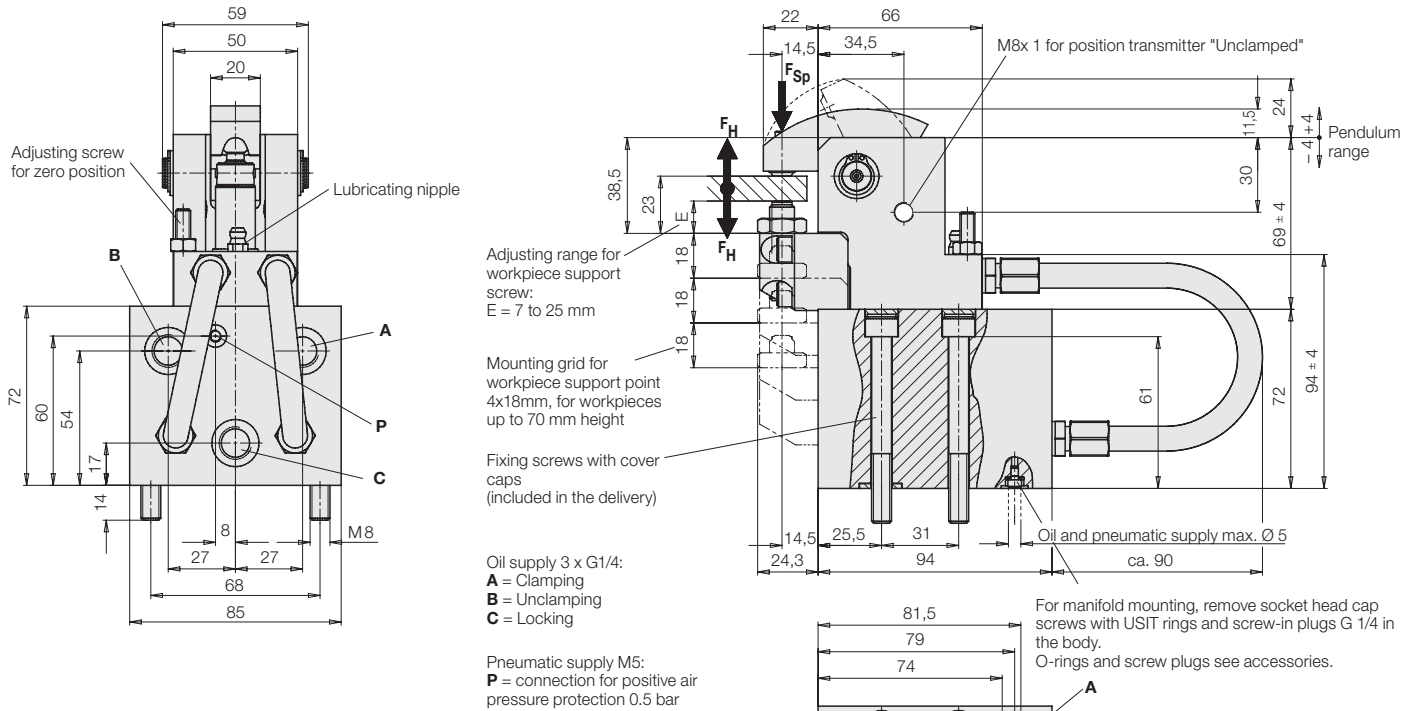
Hose at the side



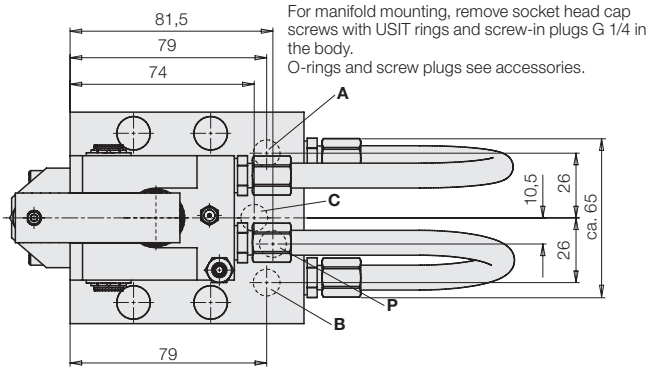
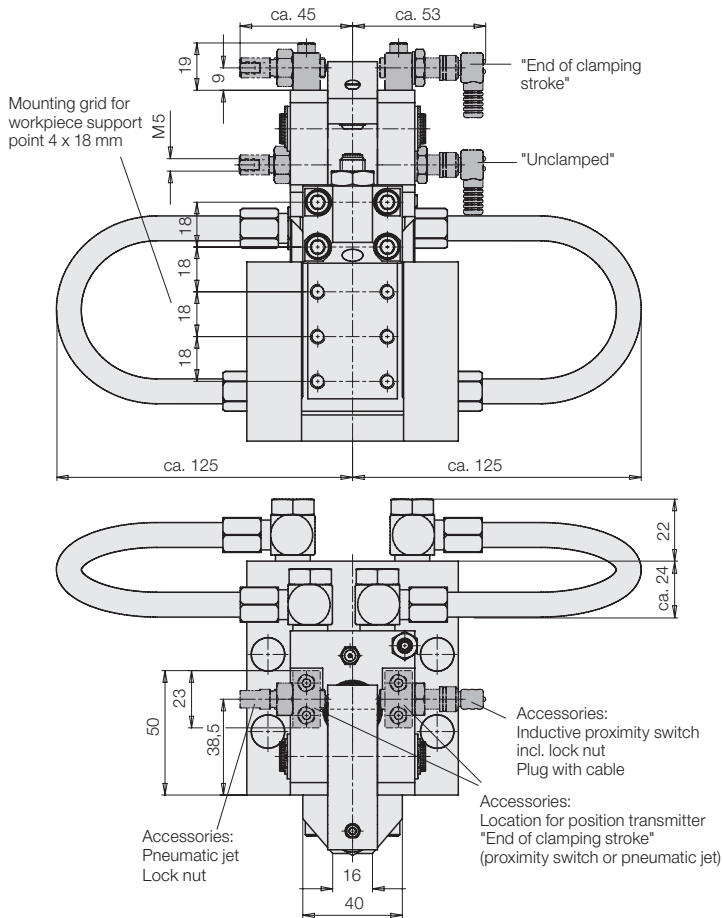
Dimensions

Technical data • Accessories

Design: Hose at the back



Design: Hose at the side



Technical data

Clamping force F_{Sp} at 250 bar	[kN]	7.5
Retention force F_H at 250 bar	[kN]	10
Min. operating pressure	[bar]	50
Contact force*	[N]	0 – 30
Pendulum range	[mm]	± 4
Oil volume clamping	[cm ³]	13.5
Oil volume unclamping	[cm ³]	8.0
Oil volume locking	[cm ³]	0.2
Max. flow rate	[cm ³ /s]	15

Part no. Hose at the back **4412977**

Part no. Hose at the side **4412978**

* depending on the adjustment of the pendulum range

Accessories

Accessories	Part no.
Screw plug G 1/4	3 off 3300821
O-ring 8 x 1.5	4 off 3000275
Inductive proximity switch	3829263
Plug with cable (5m)	3829099
Pneumatic jet with lock nut	4412997
Location for position transmitter "End of clamping stroke"	4412984

Article available on request

On request, we will check whether the article is still available.

Technical characteristics for inductive proximity switches

Operating voltage U_B	10 ... 30 V DC
Switching function	Interlock
Switching output	PNP
Material of housing	steel, corrosion resistant
Protection as per DIN 40050	IP 67
Ambient temperature	-25° ... +70 °C
Type of connection	Connector
Protected against short circuits	yes

Materials

Clamping unit: Aluminium
 Other parts: Steel
 Sealings: FKM