

# **Concentric Vise - Power Clamp Centric**

Block-type, hydraulically or pneumatically operated, double acting, size 64 and 100 mm, max. clamping force: 4.0 - 20.3kN



# **Application**

These pneumatically or hydraulically operated concentric vices can position and clamp workpieces with an accuracy of ±0.005 mm.

They are ideally suited for the series production of precision workpieces on single or multiple-clamping fixtures. The double-acting cylinder function enables both interior and exterior clamping of workpieces.

#### Description

The housings of the centric vices have a squareshaped design. Therefore, a clamping piston with a large diameter can be installed, which enables an exceptionally high clamping force in the pneumatic concentric vice. The piston force is transmitted backlash-free to the two base jaws synchronously and concentrically.

All concentric vices have an internal flow rate limitation.

# Positive air pressure connection

The most reliable protection against the penetration of liquids and dirt particles is the application of oil- and water-free positive air pressure with a slight overpressure of max. 1 bar.

#### **Versions**

- 2 sizes: 64 and 100 mm
- Hydraulically or pneumatically operated
- Max. clamping force: BG 64 - hydraulic: 4.8 kN BG100 - hydraulic: 20.3 kN BG 64 - pneumatic: 4.0 kN BG100 - pneumatic: 14.0 kN

# Options on request

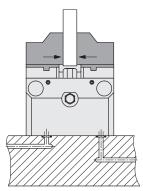
- Pneumatic workpiece contact control
- Port for central lubrication
- Electrical stroke end control
- Rapid-clamping jaw system

#### Delivery

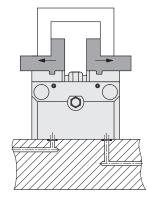
- Concentric vice
- Clamping sleeves for precise alignment of the concentric vice
- Locking screws for concentric vice
- Blind plugs to close the fixing screw bore

# **Advantages**

- Space-saving thanks to compact design
- Very high rigidity
- Low-wear due to hardened surfaces
- Repetitive clamping accuracy 0.005 mm
- Suitable for interior or exterior clamping
- Manifold mounting and pipe thread as standard
- Onnection for positive air pressure protection as standard



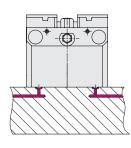
Exterior clamping application



Interior clamping application

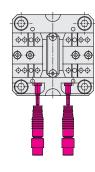
#### **Options on request**

Port for central lubrication see page 6



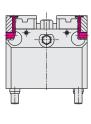
**Electrical stroke** end control

see page 6



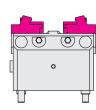
Pneumatic workpiece contact control

see page 7



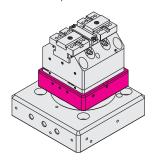
Rapid-clamping jaw system

see page 7



Zero point adaptation

on request



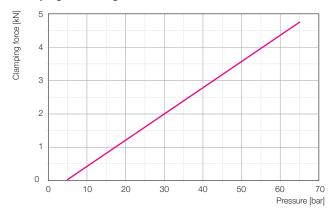
# Technical data • Dimensions

Technical data		
Max. clamping force	[kN]	4.8
Max. operating pressure	[bar]	65
Min. operating pressure	[bar]	5
Stroke per clamping jaw	[mm]	2.5
Clamping range	[mm]	0 – 55
Weight	[kg]	1.4

[°C] 4ZBA AAA00000 Part no.

5 - 60

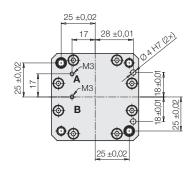
# Clamping force diagram



The specified clamping force acts at maximum pressure and is used to calculate side loads that can be transferred. Only half of the specified clamping force may be used to determine the transferable machining forces that can be transferred across a clamping jaw.

#### **Dimensions**

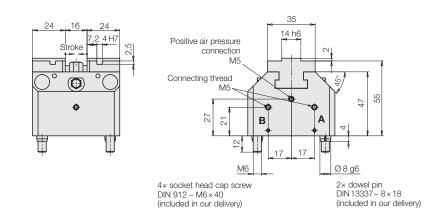
Temperature range



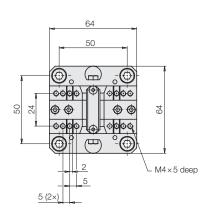
Exterior clamping: **A** = Clamping / **B** = Unclamping

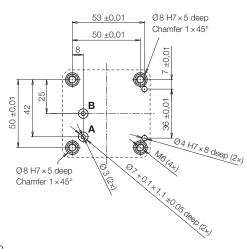
Interior clamping:

**B** = Clamping / **A** = Unclamping



# **Connecting scheme**





Alternatively, the concentric vise can also be aligned with 2ר4 mm dowel pins.

Required accessories for manifold connection with O-ring (see accessories page 10):  $2 \times$  O-rings  $4 \times 1.5$ 

0 10 20

Clamping force diagram

#### **Technical data** 20.25 [kN] Max. clamping force Max. operating pressure [bar] 90 Min. operating pressure [bar] 5 Stroke per clamping jaw [mm] 3 Clamping range [mm] 0 - 90Weight 5 [kg] Temperature range 5 - 60[°C] 4ZBA AAB00000 Part no.

# 

30

40 50

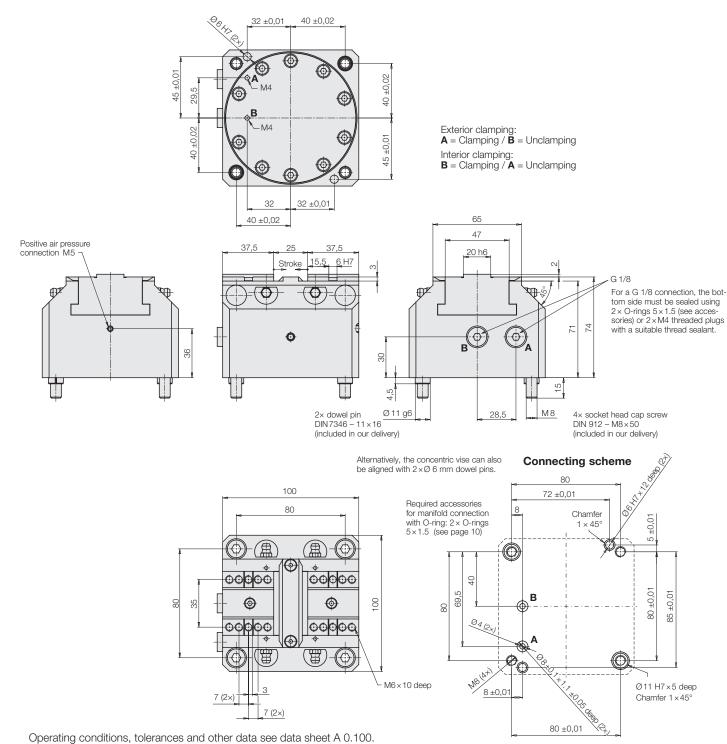
The specified clamping force acts at maximum pressure and is used to calculate side loads that can be transferred. Only half of the specified clamping force may be used to determine the transferable machining forces that can be transferred across a clamping jaw.

60 70 80

100

90

#### **Dimensions**



# Pneumatic version size 64

# Technical data • Dimensions

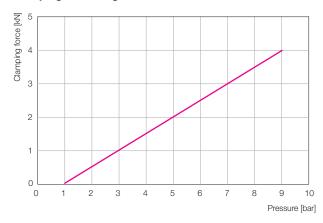
# **Technical data**

Max. clamping force	[kN]	4
Max. operating pressure	[bar]	9
Min. operating pressure	[bar]	1
Stroke per clamping jaw	[mm]	2.5
Clamping range	[mm]	0 – 55
Weight	[kg]	1.2
Temperature range	[°C]	5 – 60

Part no.

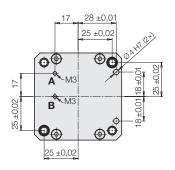
4ZBA CAA00000

# Clamping force diagram



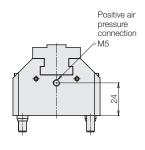
The specified clamping force acts at maximum pressure and is used to calculate side loads that can be transferred. Only half of the specified clamping force may be used to determine the transferable machining forces that can be transferred across a clamping jaw.

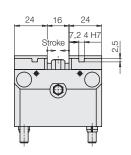
# **Dimensions**

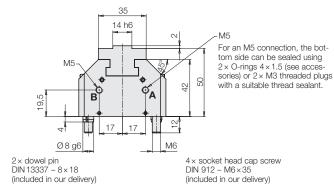


Exterior clamping:  $\mathbf{A} = \text{Clamping} / \mathbf{B} = \text{Unclamping}$ 

Interior clamping: **B** = Clamping / **A** = Unclamping





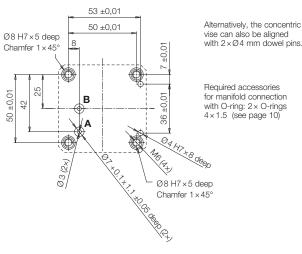


# 50 **(4)** -00|oc 9 8

M4×5 deep

64

# Connecting scheme

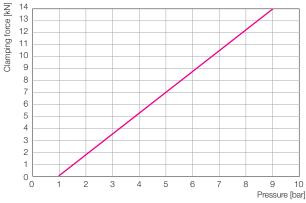


#### **Technical data**

Max. clamping force	[kN]	14
Max. operating pressure	[bar]	9
Min. operating pressure	[bar]	1
Stroke per clamping jaw	[mm]	2.5
Clamping range	[mm]	0 – 90
Weight	[kg]	4
Temperature range	[°C]	5 – 60

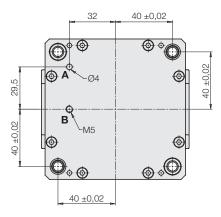
4ZBA CAB00000 Part no.

# Clamping force diagram



The specified clamping force acts at maximum pressure and is used to calculate side loads that can be transferred. Only half of the specified clamping force may be used to determine the transferable machining forces that can be transferred across a clamping jaw.

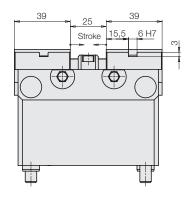
#### **Dimensions**

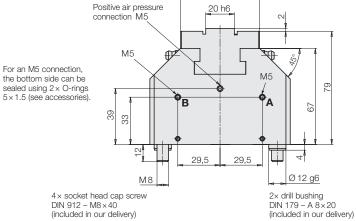


Exterior clamping: **A** = Clamping / **B** = Unclamping

Interior clamping:

**B** = Clamping / **A** = Unclamping





 $4 \times$  socket head cap screw DIN 912 – M8  $\times$  40 (included in our delivery)

# **Connecting scheme**

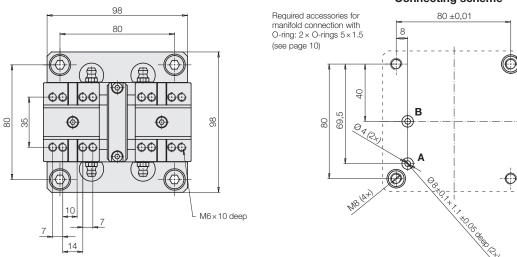
Ø 12 H7 × 5 deep (2×)

Chamfer 1×45°

±0,01

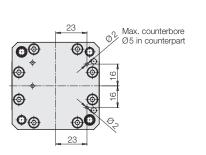
8

55

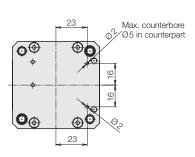


# Port for central lubrication

# Size 64

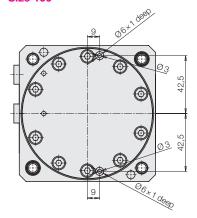


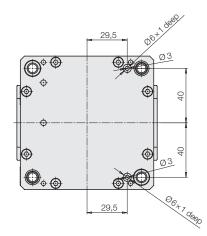
# Hydraulic



# **Pneumatic**

# Size 100





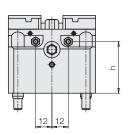
# Electrical stroke end control with proximity switch

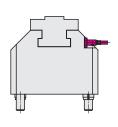
Size 64

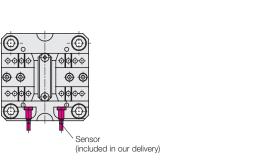
Version		Hydraulic	Pneumatic
h	[mm]	37.9	32.9

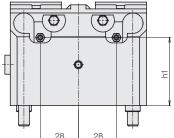
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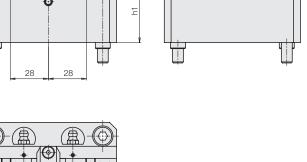
Version		Hydraulic	Pneumatic
h1	[mm]	50	53.5

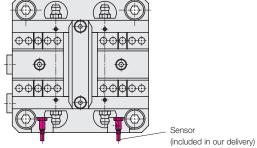












# Pneumatic workpiece contact control

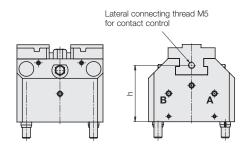
# Pneumatic workpiece contact control

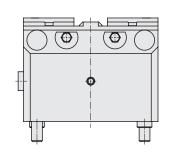
# Size 64

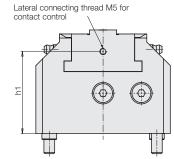
Version		Hydraulic	Pneumatic
h	[mm]	42	37

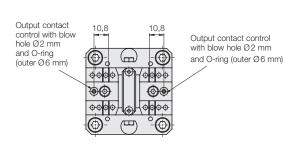
#### Size 100

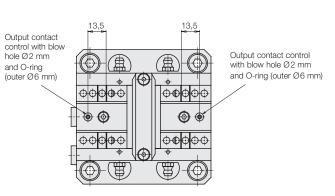
Version		Hydraulic	Pneumatic
h1	[mm]	61	64











In the version with pneumatic workpiece contact control, pneumatic pressure is fed into both base jaws via the M5 lateral connecting thread, which is then transferred to the clamping jaw by means of an O-ring sealing. The blow hole in the clamping jaw should not be larger than Ø2 mm.

# Signal conversion: Pneumatic-electric

An electro-pneumatic measuring device can either signal the pressure increase or a drop of the air flow rate.

#### 1. Pressure switches

The pressure switch signals the pressure increase when closing a blow

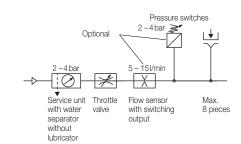
It is important that the pressure difference between the open and closed blow hole is big enough to receive a process-safe message.

#### 2. Flow meter

The flow meter signals the drop of the air flow rate when closing a blow hole. The flow meter should have a digital display and one adjustable limit switch (e.g., type SFAB of FESTO).

The switching threshold is set to a mean value between the open and

We recommend flow measurement if only one pneumatic line is available for several elements.

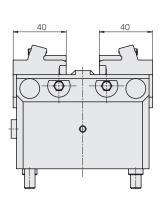


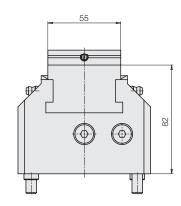
# Rapid-clamping jaw system

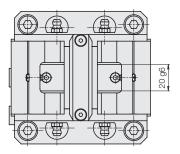
#### **Size 100**

#### Hydraulic version

For additional dimensions and technical data on the hydraulic version, see page 3.



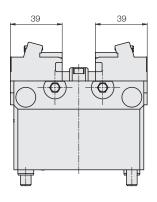


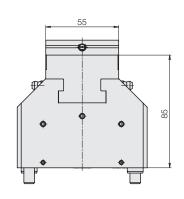


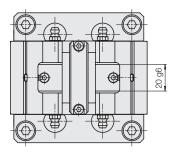
# Size 100

# **Pneumatic version**

For additional dimensions and technical data on the pneumatic version, see page 5.





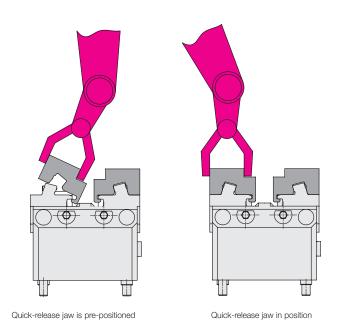


# Automated change of clamping jaws

# Description

The rapid-clamping jaw system is ideal for quick manual changeover of the clamping jaws and especially for automated clamping jaw changes by the robot, as shown in the example for exterior clamping.

The interface must be designed differently for interior clamping.



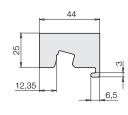
#### **Functional principle**

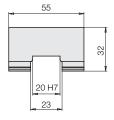
The clamping jaw is pre-fixed in the base jaw by a contact piece. When clamping a workpiece, both clamping jaws are pressed against the bevel of the base jaw. This ensures a secure hold when changing workpieces so additional fixing screws are not needed.

# Quick-release jaws blank

Material: 16MnCr5 soft

# Size 100





Max. jaw height 25 mm at max. operating pressure

# Accessories

O-rings	Part no.
O-ring 4 × 1.5	3002167
O-ring 5 × 1.5	3001 147

Spare parts	Part no.
Blind plugs, chamfered Ø11.3 mm for size 64	35381481
Blind plugs, chamfered Ø15.3 mm for size 100	35381480

Seal kits	Part no.
Size 64 hydraulic	01321161
Size 100 hydraulic	01321162
Size 64 pneumatic	01321159
Size 100 pneumatic	01321160

# Clamping jaws blank

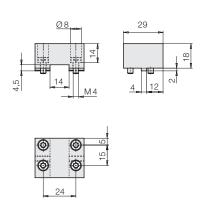
Material: 16MnCr5 soft

Fixing screws included in delivery

#### Size 64

# Part no. 35381473

1 set (2 pieces) clamping jaw blanks



Max. jaw height 18 mm at max. operating pressure

# **Special lubricating grease** 500 g cartridge

The special lubricating grease is characterized by the following properties:

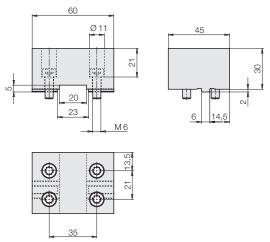
- Highest lubrication performance
- Very high pressure resistance
- Prevention of stick-slip
- Constant low coefficients of friction, especially with high surface pressure
- Imparts emergency running properties
- Good corrosion protection

# Part no. 9001800

# Size 100

# Part no. 35381474

1 set (2 pieces) clamping jaw blanks



Max. jaw height 30 mm at max. operating pressure